

In the Claims

This listing of claims will replace all prior versions, and listings, of claims in the application:

Listing of Claims

1. (Currently Amended) A coordinate positioning method, which is applied in a thin film positioning device for detecting a coordinate value of a contact point under an environment of periodic noises, comprising the steps of:

obtaining a first sampling value of the contact point at a first time point;

obtaining a second sampling value of the contact point at a second time point, wherein the interval between the first time point and the second time point is ~~roughly~~ substantially a half of the period of the periodic noise;

determining if ~~the~~ an absolute value of the difference between the first sampling value and the second sampling value is smaller than a first threshold value or not: if not, ~~neglect~~ neglecting this contact point and ~~end~~ ending the process of this method;

~~obtain~~ obtaining a third sampling value of the contact point at a third time point, wherein the interval between the third time point and the first time point is ~~roughly~~ substantially a multiple of the period of the periodic noise;

determining if ~~the~~ an absolute value of the difference between the first sampling value and the third sampling value is smaller than a second threshold value or not: if not, ~~neglect~~ neglecting this contact point and ~~end~~ ending the process of this method; and

use using the average value of the first sampling value and the second sampling value to obtain the coordinate of the contact point.

2. (Original) The positioning method according to claim 1, wherein the first threshold value is larger than the second threshold value.

3. (Currently Amended) A coordinate positioning method, which is applied in a thin film positioning device for detecting a coordinate value of a contact point under an environment of periodic noises, comprising the steps of:

obtaining a first sampling value of the contact point at a first time point;

obtaining a second sampling value of the contact point at a second time point;

determining if ~~the~~ an absolute value of the difference between the first sampling value and the second sampling value is smaller than a first threshold value or not: if not, ~~neglect~~ neglecting this contact point and ~~end~~ ending the coordinate positioning process ~~of this method~~;

~~obtain~~ obtaining a third sampling value of the contact point at a third time point;

determining if ~~the~~ an absolute value of the difference between the first sampling value and the third sampling value is smaller than a second threshold value or not: if not, neglect this contact point and end the process of this method; and

use using the average value of the first sampling value and the second sampling value to obtain the coordinate of the contact point.

4. (Original) The positioning method according to claim 3, wherein the first threshold value is larger than the second threshold value.

5. (Currently Amended) The positioning method according to claim 3, wherein the interval between the first time point and the second time point is ~~roughly~~ substantially a half of the period of the periodic noise.

6. (Currently Amended) The positioning method according to claim 3, wherein the interval between the third time point and the first time point is ~~roughly~~ substantially a multiple of the period of the periodic noise.

7. (Currently Amended) A coordinate positioning device for detecting a coordinate value of a contact point under an environment of periodic noise, comprising:

- a thin film X which has a first X-end and a second X-end
- a thin film Y which has a first Y-end and a second Y-end;
- a first switch Y coupled to the first Y-end and a ground end;
- a second switch Y coupled to the second Y-end and a power source;
- a first switch X coupled to the first X-end and the ground end;
- a second switch X coupled to the second X-end and the power source;

~~of which~~ wherein, if a sampling point is to be sampled by the positioning device, the sampling point is the first X-end, the second X-end, the first Y-end or the second Y-end; ~~first of all~~, a first sampling value of the sampling point is obtained at a first time point while a second sampling value of the sampling point is obtained at a second time point, wherein the interval between the first time point and the second time point is ~~roughly~~ substantially a half of the period of the periodic noise;

~~secondly, wherein the coordinate positioning device determines~~ determine if the absolute value of the difference between the first sampling value and the second sampling value is smaller than a first threshold value or not: if not, the coordinate positioning device neglects ~~neglect~~ the contact point;

wherein the coordinate positioning device obtains ~~obtain~~ a third sampling value of the sampling point at a third time point, wherein the interval between the third time point and the first time point is ~~roughly~~ substantially a multiple of the period of the periodic noise;

~~next, determining~~ wherein the coordinate positioning device determines if the absolute value of the difference between the first sampling value and the third sampling value is smaller than a second threshold value or not: if not, the coordinate positioning device neglects ~~neglect~~ the contact point;

~~lastly, wherein~~ the positioning device uses the average value of the first sampling value and the second sampling value to obtain the coordinate value of the contact point.

8. (Currently amended) The coordinate positioning method ~~device~~ according to claim 7, wherein the first threshold value is larger than the second threshold value.

9. (Currently amended) The coordinate positioning method ~~device~~ according to claim 7, wherein the thin film X and the thin film Y are plane resistances.

10. (Currently amended) The coordinate positioning method device according to claim 7, wherein the first switch Y, the second switch Y, the first switch X, and the second switch X are transistors.

11. (Currently amended) The coordinate positioning method device according to claim 7, wherein when detecting an X-coordinate of the contact point, the ~~thin film~~ coordinate positioning device connects the first switch Y and the second switch Y, then chooses a sampling point at the first X-end or at the second X-end to obtain the X-coordinate of the contact point accordingly.

12. (Currently amended) The coordinate positioning method device according to claim 7, wherein when detecting an Y-coordinate of the contact point, the ~~thin film~~ coordinate positioning device connects the first switch X and the second switch X, then chooses a sampling point at the first Y-end or at the second Y-end to obtain the Y-coordinate of the contact point accordingly.